

```

//Servo
#include <Servo.h>
#include <LiquidCrystal.h>

// select the pins used on the LCD panel
LiquidCrystal lcd(8, 9, 4, 5, 6, 7);
Servo myservo1;
Servo myservo2;

#define LEFT    0
#define UP      1
#define DOWN    2
#define RIGHT   3
#define SELECT  4
#define NONE    5

#define analogswitch A0

int pattern;
int pushbutton;
int a;
int b;

int button() {
    pushbutton = (analogRead(analogswitch) / 4);
    if (pushbutton >= 240) return NONE;
    if (pushbutton < 20) return  RIGHT;
    if (pushbutton < 70) return  UP;
    if (pushbutton < 120) return DOWN;
    if (pushbutton < 170) return LEFT;
    if (pushbutton < 240) return SELECT;
    //return NONE;
}

void setup() {
    //myservo1.attach(12);
    //myservo2.attach(13);
    Serial.begin(250000);
    lcd.begin(16, 2);           // start the library
    lcd.setCursor(0, 0);
    lcd.write("button");
}

```

```
}
```

```
void loop() {  
  pattern = button();  
  a = myservo1.attached();  
  b = myservo2.attached();  
  if (pattern == NONE) {  
    myservo1.detach();  
    myservo2.detach();  
  }  
  else {  
    switch (pattern) {  
      case LEFT:  
        myservo1.attach(12);  
        myservo2.attach(13);  
        myservo1.write(34);  
        myservo2.write(34);  
        lcd.setCursor(0, 1);  
        lcd.write("LEFT");  
        lcd.write("    ");  
        break;  
  
      case UP:  
        myservo1.attach(12);  
        myservo2.attach(13);  
        myservo1.write(60);  
        myservo2.write(60);  
        lcd.setCursor(0, 1);  
        lcd.write("UP");  
        lcd.write("    ");  
        break;  
  
      case DOWN:  
        myservo1.attach(12);  
        myservo2.attach(13);  
        myservo1.write(127);  
        myservo2.write(127);  
        lcd.setCursor(0, 1);  
        lcd.write("DOWN");  
        lcd.write("    ");  
        break;  
  
      case RIGHT:
```

```
myservo1.attach(12);
myservo2.attach(13);
myservo1.write(150);
myservo2.write(150);
lcd.setCursor(0, 1);
lcd.write("RIGHT");
lcd.write(" ");
break;
```

```
case SELECT:
```

```
myservo1.attach(12);
myservo2.attach(13);
myservo1.write(180);
myservo2.write(180);
lcd.setCursor(0, 1);
lcd.write("SELECT");
lcd.write(" ");
break;
```

```
case NONE:
```

```
lcd.setCursor(0, 1);
lcd.write("NONE");
lcd.write(" ");
break;
```

```
}
```

```
}
```

```
serial();
```

```
}
```

```
void serial() {
```

```
Serial.print("pushbutton");
```

```
Serial.print(" ");
```

```
Serial.print(pushbutton);
```

```
Serial.print(" ");
```

```
Serial.print("a");
```

```
Serial.print(" ");
```

```
Serial.print(a);
```

```
Serial.print(" ");
```

```
Serial.print("b");
```

```
Serial.print(" ");
```

```
Serial.println(b);
```

```
}
```

```

//sample_LCD_Keypad
#include <LiquidCrystal.h>

/*****

This program will test the LCD panel and the buttons
Mark Bramwell, July 2010

*****/

// select the pins used on the LCD panel
LiquidCrystal lcd(8, 9, 4, 5, 6, 7);

// define some values used by the panel and buttons
int lcd_key    = 0;
int adc_key_in = 0;
#define btnRIGHT  0
#define btnUP     1
#define btnDOWN   2
#define btnLEFT   3
#define btnSELECT 4
#define btnNONE   5

// read the buttons
int read_LCD_buttons()
{
  adc_key_in = analogRead(0);    // read the value from the sensor
  // my buttons when read are centered at these valies: 0, 144, 329, 504, 741
  // we add approx 50 to those values and check to see if we are close
  if (adc_key_in > 1000) return btnNONE; // We make this the 1st option for speed reasons
  since it will be the most likely result
  // For V1.1 us this threshold
  if (adc_key_in < 50)   return btnRIGHT;
  if (adc_key_in < 250) return btnUP;
  if (adc_key_in < 450) return btnDOWN;
  if (adc_key_in < 650) return btnLEFT;
  if (adc_key_in < 850) return btnSELECT;

  // For V1.0 comment the other threshold and use the one below:
  /*
  if (adc_key_in < 50)   return btnRIGHT;
  if (adc_key_in < 195) return btnUP;
  if (adc_key_in < 380) return btnDOWN;

```

```

    if (adc_key_in < 555) return btnLEFT;
    if (adc_key_in < 790) return btnSELECT;
*/

return btnNONE; // when all others fail, return this...
}

void setup()
{
    lcd.begin(16, 2);           // start the library
    lcd.setCursor(0, 0);
    lcd.print("Push the buttons"); // print a simple message
}

void loop()
{
    lcd.setCursor(9, 1);       // move cursor to second line "1" and 9 spaces over
    lcd.print(millis() / 1000); // display seconds elapsed since power-up

    lcd.setCursor(0, 1);       // move to the begining of the second line
    lcd_key = read_LCD_buttons(); // read the buttons

    switch (lcd_key)           // depending on which button was pushed, we perform an
action
    {
        case btnRIGHT:
            {
                lcd.print("RIGHT ");
                break;
            }
        case btnLEFT:
            {
                lcd.print("LEFT  ");
                break;
            }
        case btnUP:
            {
                lcd.print("UP    ");
                break;
            }
        case btnDOWN:

```

```
{
    lcd.print("DOWN ");
    break;
}
case btnSELECT:
{
    lcd.print("SELECT");
    break;
}
case btnNONE:
{
    lcd.print("NONE ");
    break;
}
}
}
```

```

//Ethernet1
#include <SPI.h>    // for Ethernet.h
#include <Ethernet.h> // for Ethernet

#define LED1PIN (7)
#define LED2PIN (8)
#define LED3PIN (9)

#define LINEBUFFERSIZE (128)
#define DELIMITER("&")

unsigned char MACADDRESS[] = { 0x8C, 0x73, 0x6E, 0xE0, 0xB1, 0xED };
unsigned char IPADDRESS[] = { 172, 17, 25, 199 };
EthernetServer g_server(80);

void setup()
{
  Ethernet.begin(MACADDRESS, IPADDRESS);
  g_server.begin();
  pinMode(LED1PIN, OUTPUT);
  pinMode(LED2PIN, OUTPUT);
  pinMode(LED3PIN, OUTPUT);
  // Serial.begin(9600);
}

// HTML 出力
void PrintHtml( EthernetClient& client, boolean led1, boolean led2, boolean led3, int speed )
{
  client.println("HTTP/1.1 200 OK");
  client.println("Content-Type: text/html");
  client.println();

  client.println("<!DOCTYPE HTML PUBLIC "-//W3C//DTD HTML 4.01  

Transitional//EN" "http://www.w3.org/TR/html4/loose.dtd">");
  client.println("<html lang=ja>");
  client.println("<head>");
  client.println("<meta http-equiv=Content-Type content=text/html; charset=UTF-  

8">");
  client.println("<meta http-equiv=Content-Style-Type content=text/css">");
  client.println("<title></title>");
  client.println("</head>");
  client.println("<body>");

```

```

client.println("<p>");
client.print("LED1 : "); client.print( led1 ? "ON" : "off" ); client.println("<br>");
client.print("LED2 : "); client.print( led2 ? "ON" : "off" ); client.println("<br>");
client.print("LED3 : "); client.print( led3 ? "ON" : "off" ); client.println("<br>");
client.println("<br>");
client.println("速 さ : ");
client.println(speed);
client.println("</p>");

client.println("<hr>");

client.println("<form method='post' action='/'>");
client.print("<input type='checkbox' name='led1' value='1'>"); if(led1){ client.print("
checked"); } client.println(">LED1<br>");
client.print("<input type='checkbox' name='led2' value='1'>"); if(led2){ client.print("
checked"); } client.println(">LED2<br>");
client.print("<input type='checkbox' name='led3' value='1'>"); if(led3){ client.print("
checked"); } client.println(">LED3<br>");
client.println("<br>");
client.println("速 さ <br>");
client.println("1 ");
client.print("<input type='radio' name='speed' value='1'>");
if(1==speed){ client.print(" checked"); } client.println("> ");
client.print("<input type='radio' name='speed' value='2'>");
if(2==speed){ client.print(" checked"); } client.println("> ");
client.print("<input type='radio' name='speed' value='3'>");
if(3==speed){ client.print(" checked"); } client.println("> ");
client.print("<input type='radio' name='speed' value='4'>");
if(4==speed){ client.print(" checked"); } client.println("> ");
client.print("<input type='radio' name='speed' value='5'>");
if(5==speed){ client.print(" checked"); } client.println("> ");
client.print("<input type='radio' name='speed' value='6'>");
if(6==speed){ client.print(" checked"); } client.println("> ");
client.print("<input type='radio' name='speed' value='7'>");
if(7==speed){ client.print(" checked"); } client.println("> ");
client.print("<input type='radio' name='speed' value='8'>");
if(8==speed){ client.print(" checked"); } client.println("> ");
client.print("<input type='radio' name='speed' value='9'>");
if(9==speed){ client.print(" checked"); } client.println("> ");
client.println(" 10<br>");
client.println("<br>");
client.println("<input type='submit' value='送信'>");
client.println("<input type='reset' value='リセツト'></form>");

```



```

client.println("<hr>");

client.println("</body>");
client.println("</html>");
}

```

```

boolean AnalyzeLineString( char* pszLine, boolean& rbLed1, boolean& rbLed2, boolean&
rbLed3, int& riSpeed )
{
char* pszToken = strtok(pszLine, DELIMITER);
while(pszToken)
{
if( 6 == strlen(pszToken)
&& 0 == strncmp(pszToken, "led", 3) )
{ // led?=1
if( '1' == pszToken[3] ){ rbLed1 = true; }
else if( '2' == pszToken[3] ){ rbLed2 = true; }
else if( '3' == pszToken[3] ){ rbLed3 = true; }
}
else if( 7 == strlen(pszToken)
&& 0 == strncmp(pszToken, "speed", 5) )
{ // speed=?
riSpeed = pszToken[6] - '0';
}
pszToken = strtok(NULL, DELIMITER);
}
return true;
}

```

```

boolean readHttpRequest( EthernetClient& client, boolean& rbLed1, boolean& rbLed2,
boolean& rbLed3, int& riSpeed )
{
if( !client )
{
return false;
}

```

// HTTP リクエスト空行 (¥r¥n¥r¥n) で終わる。ので、空行を探す。

```

boolean foundRNRN = false;
boolean currentLineIsBlank = true;
char szLine[LINEBUFFERSIZE];
int iIndex = 0;
while( client.connected() )

```

```

{
    if( !client.available() )
    {
        //continue;
        break;
    }

    char c = client.read();
//    Serial.print(c);
    if( '\n' == c && currentLineIsBlank )
    { // 空行発見。
        foundRNRN = true;
    }
    if( '\n' == c )
    {
        // http リクエストの 1 行の解析
        if( foundRNRN
            && 0 != iIndex )
        {
            szLine[iIndex] = '\0';
            AnalyzeLineString( szLine, rbLed1, rbLed2, rbLed3, riSpeed );
        }
        // 新しい行の始まり。
        currentLineIsBlank = true;
        iIndex = 0;
    }
    else if( '\r' != c )
    { // この行は空行ではなかった。
        currentLineIsBlank = false;
        if( foundRNRN )
        {
            if( LINEBUFFERSIZE - 1 > iIndex )
            {
                szLine[iIndex] = c;
                ++iIndex;
            }
        }
    }
}
// http リクエストの終端行の解析
if( foundRNRN
    && 0 != iIndex )
{

```

```

    szLine[iIndex] = '¥0';
    AnalyzeLineString( szLine, rbLed1, rbLed2, rbLed3, riSpeed );
}

return foundRNRN;
}

void loop()
{
    static boolean s_led1 = false;
    static boolean s_led2 = false;
    static boolean s_led3 = false;
    static int s_interval = 0;

    EthernetClient client = g_server.available();
    boolean led1 = false;
    boolean led2 = false;
    boolean led3 = false;
    int speed = 5;
    if( readHttpRequest(client, led1, led2, led3, speed) )
    {
        // Html 出力
        PrintHtml(client, led1, led2, led3, speed);

        // Web ブラウザに対して、データを取得するための時間を与える。
        delay(1);

        // コネクションを閉じる。
        client.stop();

        s_led1 = led1;
        s_led2 = led2;
        s_led3 = led3;
        // speed          |    1          9
        // 間隔[秒]        |    0.5        0.01
        // interval[ms]   | 500          10
        s_interval = (int)(500L + (speed - 1) * (10L - 500L) / (9-1));
    }

    if( s_led1 ){ digitalWrite(LED1PIN, HIGH); }
    if( s_led2 ){ digitalWrite(LED2PIN, HIGH); }
    if( s_led3 ){ digitalWrite(LED3PIN, HIGH); }
    delay(s_interval);
}

```

```
digitalWrite(LED1PIN, LOW);  
digitalWrite(LED2PIN, LOW);  
digitalWrite(LED3PIN, LOW);  
delay(s_interval);  
}
```

```
//analogread_kakunin
#include <LiquidCrystal.h>
LiquidCrystal lcd(8, 9, 4, 5, 6, 7);
#define Switch A0
int analoginput = 0;

void setup() {
  lcd.begin(16, 2);          // start the library  LCD は 16*2 マス
  lcd.setCursor(0,0);      //上から 0 左から 0
  lcd.print("Analogread"); // print a simple message 何を表示するか
}

void loop() {
  analoginput = (analogRead(Switch)/4);
  lcd.setCursor(0,1);
  lcd.print(analoginput);
  lcd.print(" ");
}
}
```

```

//servo
#include <Servo.h>
#include <LiquidCrystal.h>

// select the pins used on the LCD panel
LiquidCrystal lcd(8, 9, 4, 5, 6, 7);
Servo myservo1;
Servo myservo2;

#define LEFT    0
#define UP      1
#define DOWN    2
#define RIGHT   3
#define SELECT  4
#define NONE    5

#define analogswitch A0

int pattern = 0;
int pushbutton = 0;

int button() {
    pushbutton = (analogRead(analogswitch) / 4);
    if (pushbutton > 240) return NONE;
    if (pushbutton < 10) return  RIGHT;
    if (pushbutton < 50) return  UP;
    if (pushbutton < 100) return DOWN;
    if (pushbutton < 150) return LEFT;
    if (pushbutton < 200) return SELECT;
    // return NONE;
}

void setup() {
    myservo1.attach(19);
    myservo2.attach(11);
    Serial.begin(9600);
    lcd.begin(16, 2);           // start the library
    lcd.setCursor(0, 0);
    lcd.write("button");

}

```

```
void loop() {  
  pattern = button();  
  switch (pattern) {  
    case LEFT:  
      myservo1.write(0);  
      lcd.setCursor(0, 1);  
      lcd.write("LEFT");  
      lcd.write(" ");  
      break;  
  
    case UP:  
      myservo1.write(45);  
      lcd.setCursor(0, 1);  
      lcd.write("UP");  
      lcd.write(" ");  
      break;  
  
    case DOWN:  
      myservo1.write(135);  
      lcd.setCursor(0, 1);  
      lcd.write("DOWN");  
      lcd.write(" ");  
      break;  
  
    case RIGHT:  
      myservo1.write(180);  
      lcd.setCursor(0, 1);  
      lcd.write("RIGHT");  
      lcd.write(" ");  
      break;  
  
    case SELECT:  
      myservo1.write(90);  
      lcd.setCursor(0, 1);  
      lcd.write("SELECT");  
      lcd.write(" ");  
      break;  
  
    case NONE:  
      lcd.setCursor(0, 1);  
      lcd.write("NONE");  
      lcd.write(" ");
```

